

P1. a. Current basis = $\{x_1, x_3\} \Rightarrow x_2 = x_4 = 0$ at current BFS:

$$\begin{array}{l} -x_1 + 4x_3 = 13 \\ 2x_1 = 2 \end{array} \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow x_1 = 1, x_3 = \frac{14}{4} = \frac{7}{2}$$

$$\Rightarrow \text{current BFS} = (1, 0, \frac{7}{2}, 0).$$

b. $\vec{d}^{x_2} = (d_{x_1}, 1, d_{x_3}, 0)$

$$-d_{x_1} + 4d_{x_3} = -1$$

$$2d_{x_1} = -6$$

$$\Rightarrow d_{x_1} = -3, d_{x_3} = -1$$

$$\Rightarrow \vec{d}^{x_2} = (-3, 1, -1, 0)$$

$$\vec{d}^{x_4} = (d_{x_1}, 0, d_{x_3}, 1)$$

$$-d_{x_1} + 4d_{x_3} = -21$$

$$2d_{x_1} = 2$$

$$\Rightarrow d_{x_1} = 1, d_{x_3} = -5$$

$$\Rightarrow \vec{d}^{x_4} = (1, 0, -5, 1).$$

c. $\bar{c}_{x_2} = -30 + 1 = -29$

$\Rightarrow \vec{d}^{x_2}$ not improving

$$\bar{c}_{x_4} = 10$$

$\Rightarrow \vec{d}^{x_4}$ improving.

d. Choose \vec{d}^{x_4} : x_4 is the entering variable

$$\lambda_{\max} = \min \left\{ \frac{7/2}{5} \right\} = \frac{7}{10} \quad x_3 \text{ is the leaving variable.}$$

$$\Rightarrow \text{new BFS} = (1, 0, \frac{7}{2}, 0) + \frac{7}{10}(1, 0, -5, 1) = \left(\frac{17}{10}, 0, 0, \frac{7}{10} \right)$$

$$\text{new basis} = \{x_1, x_4\}.$$

P2. a. min $5y_1 + 8y_2$

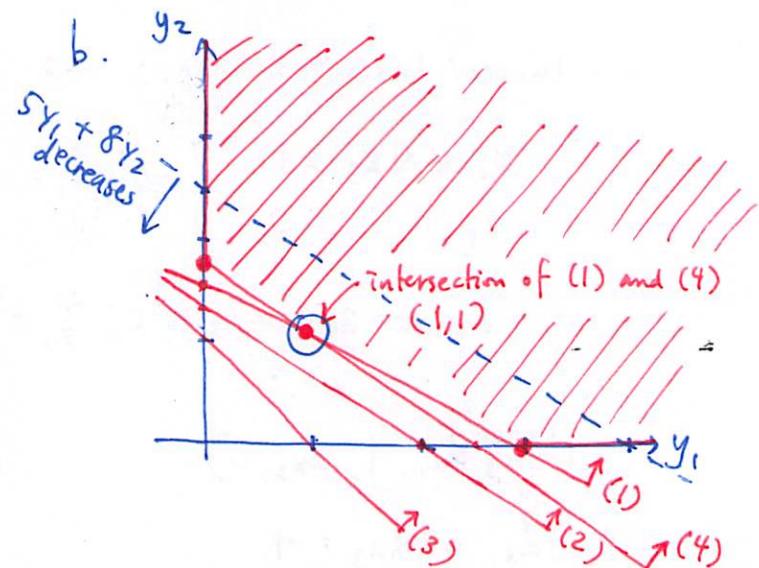
s.t. $y_1 + 2y_2 \geq 3$ (1)

$2y_1 + 3y_2 \geq 4$ (2)

$y_1 + y_2 \geq 1$ (3)

$2y_1 + 3y_2 \geq 5$ (4)

$y_1, y_2 \geq 0$.



optimal soln: $y_1^* = 1, y_2^* = 1$.

c. Dual complementary slackness: dual constraint not active
 \Rightarrow corresponding primal variable = 0.

From part b, it is clear that constraints (2) and (3) are not active at (1,1). \Rightarrow In an optimal solution to [P], we must have $x_2 = x_3 = 0$.

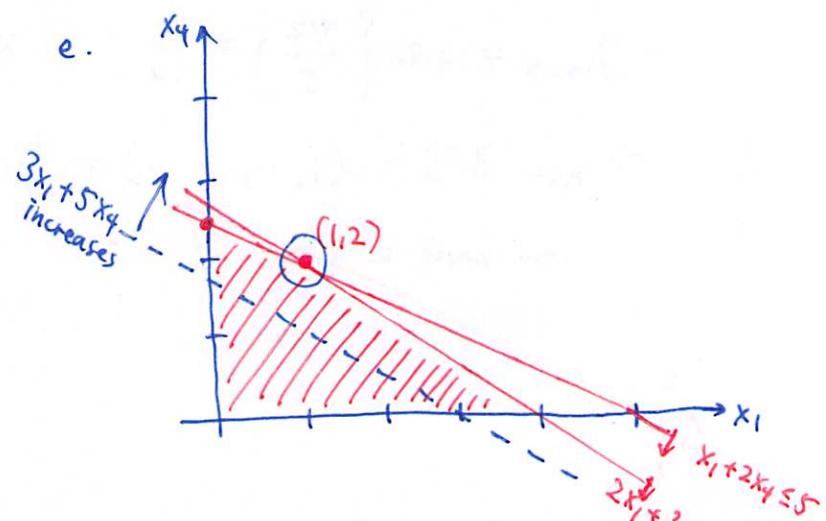
d. modified [P]:

max $3x_1 + 5x_4$

s.t. $x_1 + 2x_4 \leq 5$

$2x_1 + 3x_4 \leq 8$

$x_1, x_4 \geq 0$



optimal soln to modified [P]:

$x_1^* = 1, x_4^* = 2$

optimal soln. to [P]: $(1, 0, 0, 2)$

P3. Symbolic input parameters:

c = cost of crude oil per 1000 barrels

p_a = price of unprocessed aviation fuel per 1000 barrels

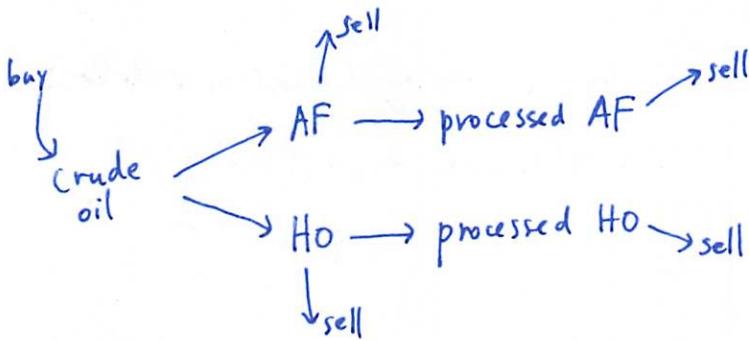
p_h = price of unprocessed heating oil per 1000 barrels

q_a = price of processed aviation fuel per 1000 barrels

q_h = price of processed heating oil per 1000 barrels

t_a = time to process aviation fuel per 1000 barrels

t_h = time to process heating oil per 1000 barrels



Decision variables: (in 1000 barrels)

z = amt. of crude oil to buy

x_a = amt. of unprocessed AF to sell

x_h = amt. of unprocessed HO to sell

y_a = amt. of processed AF to sell

y_h = amt. of processed HO to sell.

Model:

$$\text{max } p_a x_a + p_h x_h + q_a y_a + q_h y_h - cz \quad (\text{total profit})$$

$$\text{s.t. } \frac{3}{4}z = x_a + y_a \quad (\text{crude oil} \rightarrow \text{AF})$$

$$\frac{1}{4}z = x_h + y_h \quad (\text{crude oil} \rightarrow \text{HO})$$

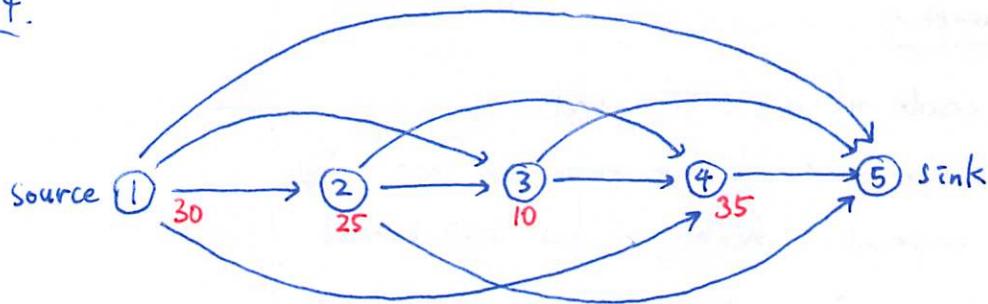
$$t_a y_a + t_h y_h \leq T \quad (\text{cracker time})$$

$$z \leq B \quad (\text{available crude oil})$$

$$x_a, y_a, x_h, y_h, z \geq 0.$$

B = available crude oil, in 1000s.

p4.



vertices \leftrightarrow quarters.

numbers in red next to vertices = demand in that quarter

Arc (i,j) represents: "produce in quarter i to cover demand in quarters $i, \dots, j-1$ ".

For example, arc $(1,3)$: produce $30 + 25$ in quarter 1

30 units used immediately to satisfy demand in quarter 1

25 units held over to satisfy demand in quarter 2.

$$\text{total cost: } 100 + 3(30+25) + 5(25) = 390.$$

<u>arc</u>	<u>costs</u>
$(1,2)$	$100 + 3(30)$
$(1,3)$	$100 + 3(30+25) + 5(25)$
$(1,4)$	$100 + 3(30+25+10) + 5(25) + (5+5)(10)$
$(1,5)$	$100 + 3(30+25+10+35) + 5(25) + (5+5)(10) + (5+5+5)(10)$
$(2,3)$	$100 + 3(25)$
$(2,4)$	$100 + 3(25+10) + 5(10)$
$(2,5)$	$100 + 3(25+10+35) + 5(10) + (5+5)(35)$
$(3,4)$	$100 + 3(10)$
$(3,5)$	$100 + 3(10+35) + 5(35)$
$(4,5)$	$100 + 3(35)$

demand in quarter 3 has to be held for 2 quarters.

A shortest path from vertex 1 to vertex 5 in the above network w/ the above arc costs corresponds to a minimum total cost production plan.

P5. The objective fn. vector $\vec{c} = (3, 11, -8, 0)$

- a. $\vec{d}^{w_4} = (1, 0, -4, 1)$ does NOT lead to a conclusion that the LP is unbounded, since its components are not all nonnegative.
- b. $\vec{d}^{w_4} = (1, 3, 0, 1)$ has associated reduced cost $\bar{c}_{w_4} = 36$.
Since the LP is minimizing, \vec{d}^{w_4} is not improving. So, even though all components of \vec{d}^{w_4} are nonnegative, we cannot conclude that the LP is unbounded.
- c. $\vec{d}^{w_4} = (1, 0, 3, 1)$ has associated reduced cost $\bar{c}_{w_4} = -21$, and so \vec{d}^{w_4} is improving, with all nonnegative components. Therefore, we can conclude that the LP is unbounded.
- d. $\vec{d}^{w_4} = (-1, 1, -2, 1)$. Similar to part a.

P6. Symbolic input parameters:

P = set of presents

C = set of children

v_{ij} = happiness of child i w/present j for $i \in C, j \in P$

b_j = # present j available for $j \in P$.

Decision variables: $x_{ij} = \#$ present j given to child i for $i \in C, j \in P$.

Model: $\max \min \left\{ \sum_{j \in P} v_{ij} x_{ij} : i \in C \right\}$

\uparrow happiness of child i

s.t. $\sum_{i \in C} x_{ij} \leq b_j$ for $j \in P$ (available presents)

$x_{ij} \geq 0$ for $i \in C, j \in P$.

convert to LP



$\max z$

s.t. $z \leq \sum_{j \in P} v_{ij} x_{ij}$ for $i \in C$

$\sum_{i \in C} x_{ij} \leq b_j$ for $j \in P$

$x_{ij} \geq 0$ for $i \in C, j \in P$.