SA402 – Dynamic and Stochastic Models Asst. Prof. Nelson Uhan

# Lesson 11. Nonstationary Poisson Processes

#### 1 Overview

- We've been looking at Poisson processes with a **stationary** arrival rate  $\lambda$ 
  - In other words,  $\lambda$  doesn't change over time
- Today: what happens when the arrival rate is nonstationary,
   i.e. the arrival rate λ(τ) a function of time τ?
  - It turns out that a stationary Poisson process with arrival rate 1 can be transformed into a **nonstationary Poisson process** with any time-dependent arrival rate

#### 2 An example

- Suppose we are conducting a time study of a helicopter maintenance facility
- Our data indicates that the facility is busier in the morning than in the afternoon:
  - In the morning (0900 1300): expected interarrival time of 0.5 hours
  - In the afternoon (1300 1700): expected interarrival time of 2 hours
- Let's say that  $\tau = 0$  corresponds to 0900
- Therefore, the arrival rate  $\lambda(\tau)$  as a function of  $\tau$  (in hours) is:

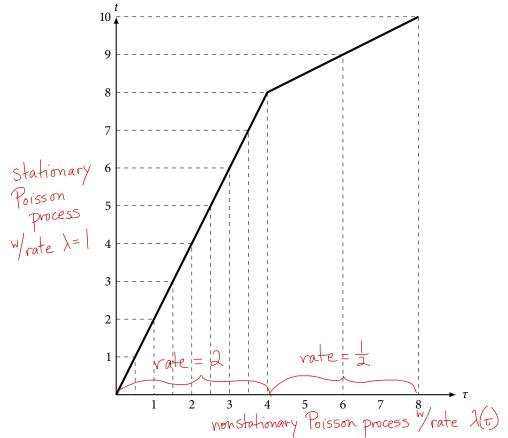
$$\lambda(\tau) = \begin{cases} 2 & \text{if } 0 \le \tau < 4 \\ \frac{1}{2} & \text{if } 4 \le \tau < 8 \end{cases}$$

 Using this, we can compute the integrated-rate function Λ(τ), or the expected number of arrivals by time τ:

$$\Lambda(\tau) = \int_{0}^{\tau} \chi(a) da$$
If  $\tau \in [0,4]$ :  $\Lambda(\tau) = \int_{0}^{\tau} \chi da = 2\tau$ 
If  $\tau \in [4,8]$ :  $\Lambda(\tau) = \int_{0}^{4} \chi da + \int_{4}^{\tau} \frac{1}{2} da = 8 + \frac{1}{2}(\tau-4) = \frac{1}{2}\tau + 6$ 

$$\Rightarrow \Lambda(\tau) = \begin{cases} 2\tau & \tau \in 0 \le \tau \le 4 \\ \frac{1}{2}\tau + 6 & \tau \notin 0 \le \tau \le 8 \end{cases}$$

• A graph of the integrated-rate function  $\Lambda(\tau)$ :



• The inverse of the integrated-rate function  $\Lambda(\tau)$ :

$$Let t = \Lambda(\tau).$$

$$If t \in [0,8): t = 2\tau \implies \tau = \frac{1}{2}t$$

$$If t \in [8,10]: t = \frac{1}{2}\tau + 6 \implies \tau = 2(t-6)$$

$$\Rightarrow \Lambda^{-1}(t) = \begin{cases} \frac{1}{2}t & \text{if } 0 \le t < 8 \\ 2(t-6) & \text{if } 8 \le t < 10 \end{cases}$$

- Key idea:  $\tau$  and t represent different time scales connected by  $t = \Lambda(\tau)$ 
  - *t* represents time scale for stationary Poisson process with arrival rate 1
  - $\circ \ \tau$  represents time scale of nonstationary Poisson process
- Why does this work? Intuitively, can be seen from the graph above

### 3 Nonstationary Poisson processes, formally

- Let  $\{Y_t; t \ge 0\}$  be a Poisson process (in particular, its output process) with arrival rate 1 and arrival times  $\{T_n; n = 0, 1, 2, ...\}$
- Define a new arrival counting process with output process  $\{Z_{\tau}; \tau \ge 0\}$ and arrival times  $\{U_n; n = 0, 1, 2, ...\}$ , where  $U_n = \Lambda^{-1}(T_n)$
- The process  $\{Z_{\tau}; \tau \ge 0\}$  is (the output process of) a **nonstationary Poisson process** with integrated-rate function  $\Lambda(\tau)$
- A nonstationary Poisson process  $\{Z_{\tau}; \tau \ge 0\}$  has the property:

$$P_{r}\left\{Z_{\tau+at}-Z_{\tau}=m\left|Z_{\tau}=k\right\}=P_{r}\left\{Z_{\tau+at}-Z_{\tau}=m\right\}$$
$$=\frac{e^{-\left[\Lambda(\tau+a\tau)-\Lambda(t)\right]}\left[\Lambda(\tau+a\tau)-\Lambda(\tau)\right]^{m}}{m!} \leftarrow P_{oisson} \bigvee_{parameter}$$
$$\frac{P_{r}\left[X_{\tau+a\tau}-X_{\tau}\right]}{m!} \leftarrow P_{oisson} \bigvee_{parameter}$$

• As a consequence, the expected number of arrivals in  $(\tau, \tau + \Delta \tau]$  is:

$$E[\mathcal{Z}_{\tau+\Delta\tau} - \mathcal{Z}_{\tau}] = \Lambda(\tau+\Delta\tau) - \Lambda(\tau)$$

- In particular, a nonstationary Poisson process satisfies the independent-increments property
- The probability distribution of the number of arrivals in  $(\tau, \tau + \Delta \tau]$  depends on both  $\Delta \tau$  and  $\tau$ 
  - $\Rightarrow$  The stationary-increments and memoryless properties no longer apply

**Example 1.** In the maintenance facility example above:

- a. What is the probability that 2 helicopters arrive between 1200 and 1400, given that 5 arrived between 0900 and 1200?
- b. What is the expected number of helicopters to arrive between 1200 and 1400?

a. 
$$\Pr\left\{Z_{5} - Z_{3} = 2 \mid Z_{3} = 5\right\} = \Pr\left\{Z_{5} - Z_{3} = 2\right\} = \frac{e^{-5/2}\left(\frac{5}{2}\right)^{2}}{2!} \approx 0.26$$
  
 $\Pr(5) - \Lambda(3) = \frac{17}{2} - 6 = \frac{5}{2}$   
b.  $E\left[Z_{5} - Z_{3}\right] = \Lambda(5) - \Lambda(3) = \frac{5}{2}$ 

**Example 2.** Think back to the Darker Image case. Suppose the copy shop is open from 0900 ( $\tau = 0$ ) to 1500 ( $\tau = 360$ ), and the arrival-rate function is

$$\lambda(\tau) = \begin{cases} 1/6 & \text{if } 0 \le \tau < 180, \\ 1/5 & \text{if } 180 \le \tau < 360 \end{cases}$$

- a. What is the expected number of customers by time  $\tau$ ?
- b. What is the probability that 5 customers arrive between 1100 and 1300?
- c. What is the expected number of customers that arrive between 1100 and 1300?
- d. If 15 customers have arrived by 1100, what is the probability that more than 60 customers will have arrived throughout the course of the day?

## 4 Why does a nonstationary Poisson process behave this way?

• Here's a short proof. Let's walk through it step-by-step:

$$\begin{aligned} \Pr\{Z_{\tau+\Delta\tau} - Z_{\tau} = m \,|\, Z_{\tau} = k\} &= \Pr\{Y_{\Lambda(\tau+\Delta\tau)} - Y_{\Lambda(\tau)} = m \,|\, Y_{\Lambda(\tau)} = k\} \quad (defn. of Z_{\tau}) \\ &= \Pr\{Y_{\Lambda(\tau+\Delta\tau)} - Y_{\Lambda(\tau)} = m\} \quad (Y_t \text{ is a stationary Poisson process, independent}) \\ &= \Pr\{Z_{\tau+\Delta\tau} - Z_{\tau} = m\} \quad (defn. of Z_{\tau}) \end{aligned}$$

Also:

$$\begin{aligned} \Pr\{Z_{\tau+\Delta\tau} - Z_{\tau} = m \,|\, Z_{\tau} = k\} &= \Pr\{Y_{\Lambda(\tau+\Delta\tau)} - Y_{\Lambda(\tau)} = m\} \quad (\text{same as above}) \\ &= \Pr\{Y_{\Lambda(\tau+\Delta\tau) - \Lambda(\tau)} = m\} \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]}[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]^m}{m!} \quad (Y_{t} \text{ is a stationary Poisson}) \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau) -$$