

Lesson 11. Nonstationary Poisson Processes

1 Overview

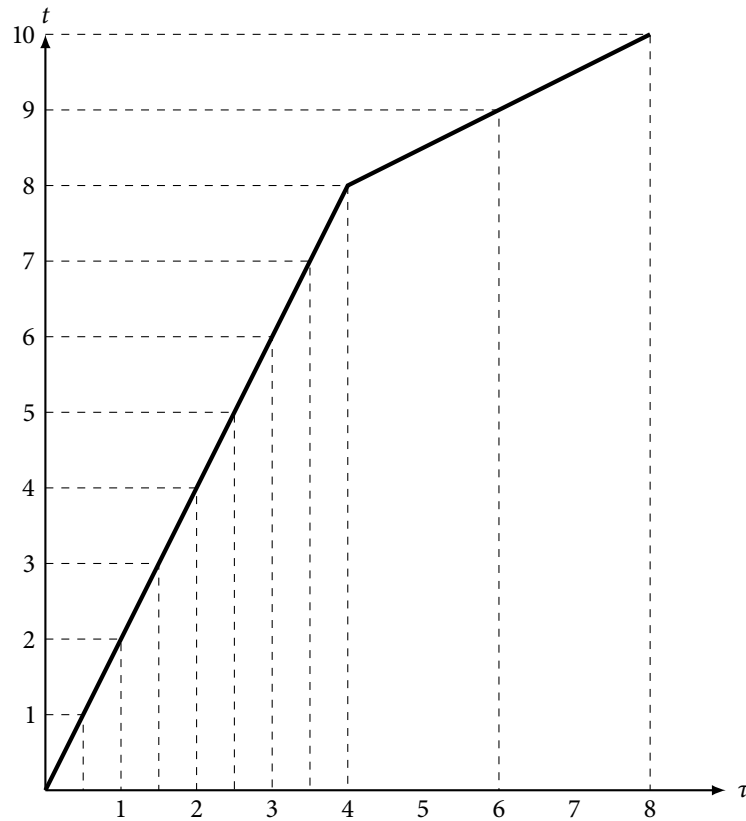
- We've been looking at Poisson processes with a **stationary** arrival rate λ
 - In other words, λ doesn't change over time
- Today: what happens when the arrival rate is **nonstationary**, i.e. the arrival rate $\lambda(\tau)$ a function of time τ ?
 - It turns out that a stationary Poisson process with arrival rate 1 can be transformed into a **nonstationary Poisson process** with any time-dependent arrival rate

2 An example

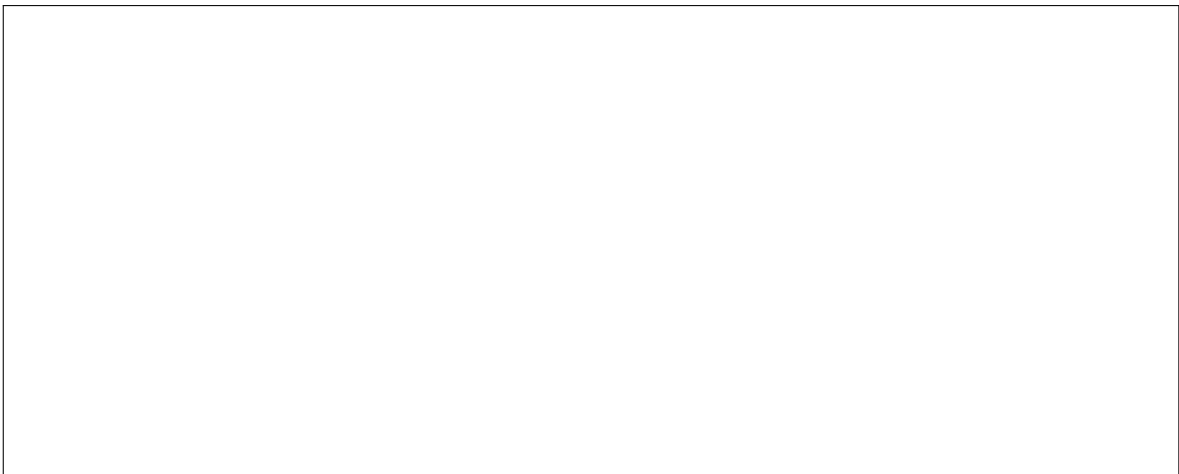
- Suppose we are conducting a time study of a helicopter maintenance facility
- Our data indicates that the facility is busier in the morning than in the afternoon:
 - In the morning (0900 – 1300): expected interarrival time of 0.5 hours
 - In the afternoon (1300 – 1700): expected interarrival time of 2 hours
- Let's say that $\tau = 0$ corresponds to 0900
- Therefore, the arrival rate $\lambda(\tau)$ as a function of τ (in hours) is:

- Using this, we can compute the **integrated-rate function** $\Lambda(\tau)$, or the expected number of arrivals by time τ :

- A graph of the integrated-rate function $\Lambda(\tau)$:



- The inverse of the integrated-rate function $\Lambda(\tau)$:



- Key idea: τ and t represent different time scales connected by $t = \Lambda(\tau)$
 - t represents time scale for stationary Poisson process with arrival rate 1
 - τ represents time scale of nonstationary Poisson process
- Why does this work? Intuitively, can be seen from the graph above

3 Nonstationary Poisson processes, formally

- Let $\{Y_t; t \geq 0\}$ be a Poisson process (in particular, its output process) with arrival rate 1 and arrival times $\{T_n; n = 0, 1, 2, \dots\}$
- Define a new arrival counting process with output process $\{Z_\tau; \tau \geq 0\}$ and arrival times $\{U_n; n = 0, 1, 2, \dots\}$, where $U_n = \Lambda^{-1}(T_n)$
- The process $\{Z_\tau; \tau \geq 0\}$ is (the output process of) a **nonstationary Poisson process** with integrated-rate function $\Lambda(\tau)$
- A nonstationary Poisson process $\{Z_\tau; \tau \geq 0\}$ has the property:

- As a consequence, the expected number of arrivals in $(\tau, \tau + \Delta\tau]$ is:

- In particular, a nonstationary Poisson process satisfies the independent-increments property
- The probability distribution of the number of arrivals in $(\tau, \tau + \Delta\tau]$ depends on both $\Delta\tau$ and τ
 \Rightarrow The stationary-increments and memoryless properties no longer apply

Example 1. In the maintenance facility example above:

- a. What is the probability that 2 helicopters arrive between 1200 and 1400, given that 5 arrived between 0900 and 1200?
- b. What is the expected number of helicopters to arrive between 1200 and 1400?

Example 2. Think back to the Darker Image case. Suppose the copy shop is open from 0900 ($\tau = 0$) to 1500 ($\tau = 360$), and the arrival-rate function is

$$\lambda(\tau) = \begin{cases} 1/6 & \text{if } 0 \leq \tau < 180, \\ 1/5 & \text{if } 180 \leq \tau < 360 \end{cases}$$

- What is the expected number of customers by time τ ?
- What is the probability that 5 customers arrive between 1100 and 1300?
- What is the expected number of customers that arrive between 1100 and 1300?
- If 15 customers have arrived by 1100, what is the probability that more than 60 customers will have arrived throughout the course of the day?

4 Why does a nonstationary Poisson process behave this way?

- Here's a short proof. Let's walk through it step-by-step:

$$\begin{aligned} \Pr\{Z_{\tau+\Delta\tau} - Z_{\tau} = m \mid Z_{\tau} = k\} &= \Pr\{Y_{\Lambda(\tau+\Delta\tau)} - Y_{\Lambda(\tau)} = m \mid Y_{\Lambda(\tau)} = k\} \\ &= \Pr\{Y_{\Lambda(\tau+\Delta\tau)} - Y_{\Lambda(\tau)} = m\} \\ &= \Pr\{Z_{\tau+\Delta\tau} - Z_{\tau} = m\} \end{aligned}$$

Also:

$$\begin{aligned} \Pr\{Z_{\tau+\Delta\tau} - Z_{\tau} = m \mid Z_{\tau} = k\} &= \Pr\{Y_{\Lambda(\tau+\Delta\tau)} - Y_{\Lambda(\tau)} = m\} \\ &= \Pr\{Y_{\Lambda(\tau+\Delta\tau) - \Lambda(\tau)} = m\} \\ &= \frac{e^{-[\Lambda(\tau+\Delta\tau) - \Lambda(\tau)]} [\Lambda(\tau + \Delta\tau) - \Lambda(\tau)]^m}{m!} \end{aligned}$$